

PL Techniques for 3D Printing



Chandakana
Nandi



Anat
Caspi



Dan
Grossman



Zachary
Tatlock

Compilers generate
our environment.

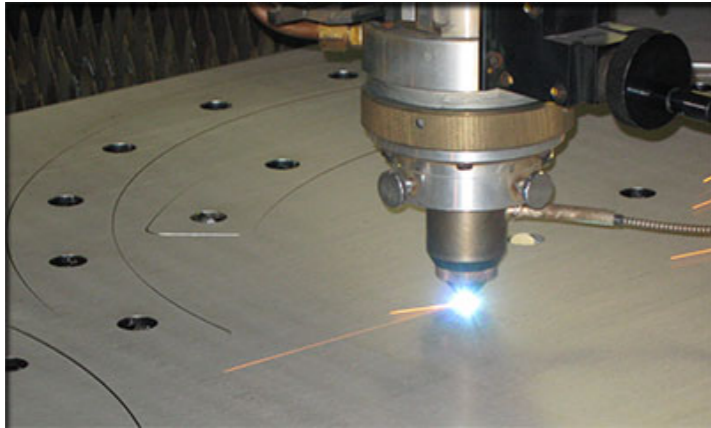






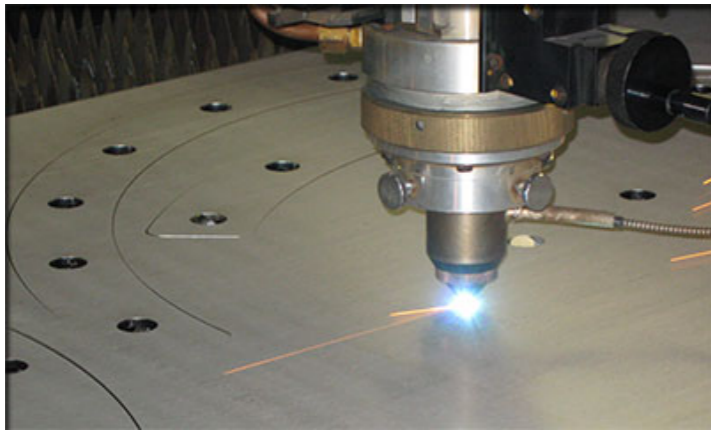


Computerized Manufacturing



CNC

Computerized Manufacturing



CNC

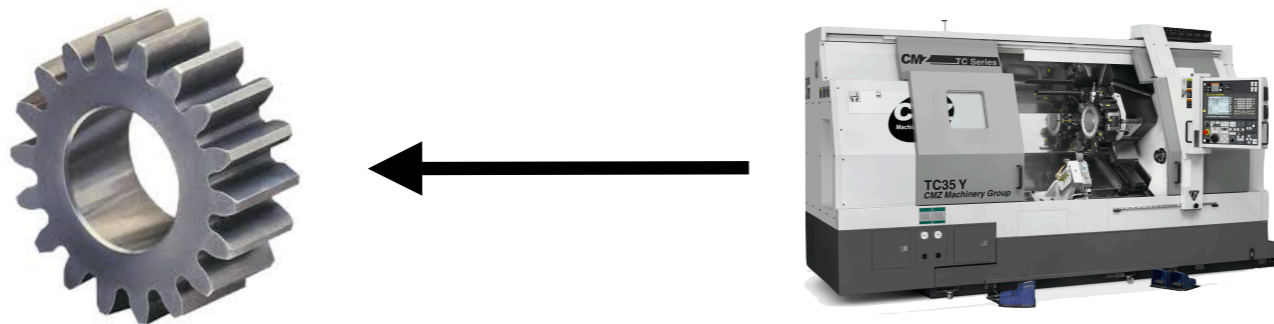


Mold Making

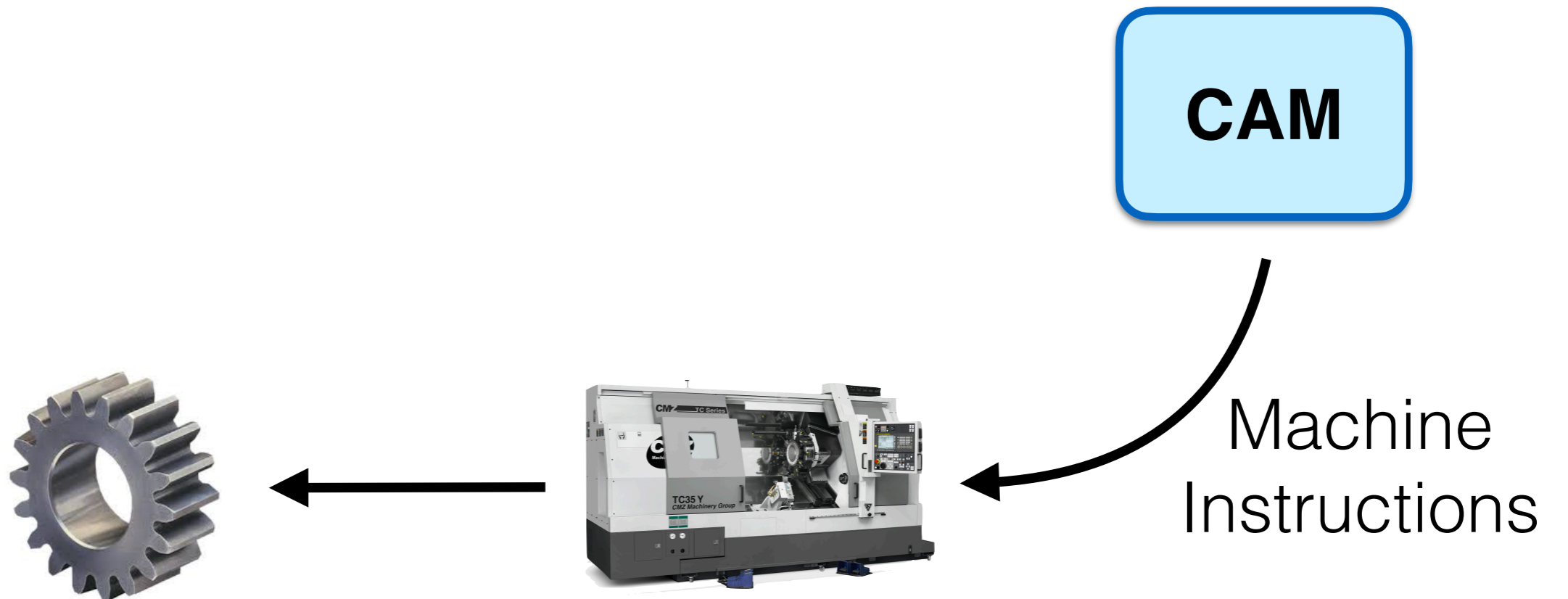


Robotic Assembly

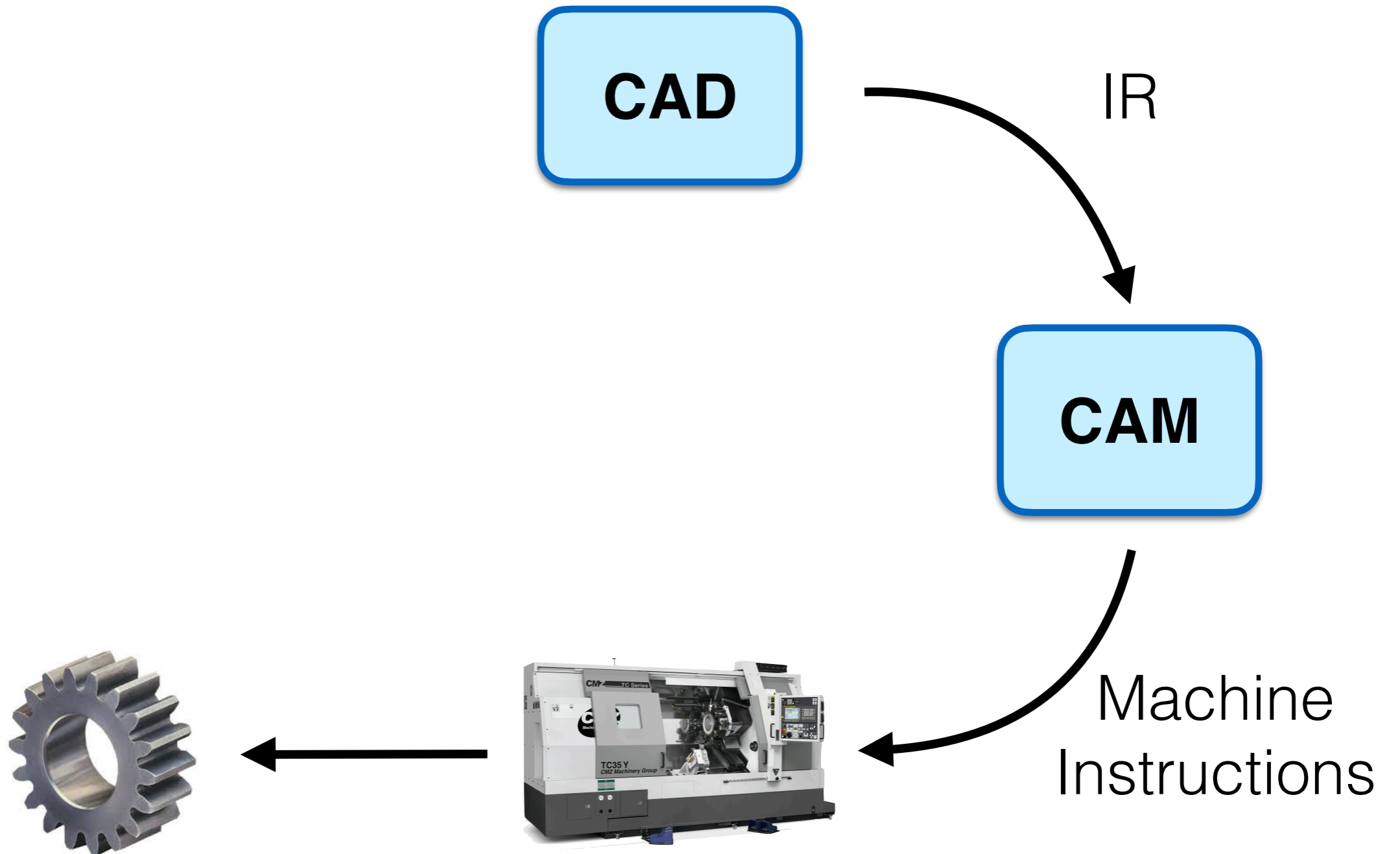
Computerized Manufacturing



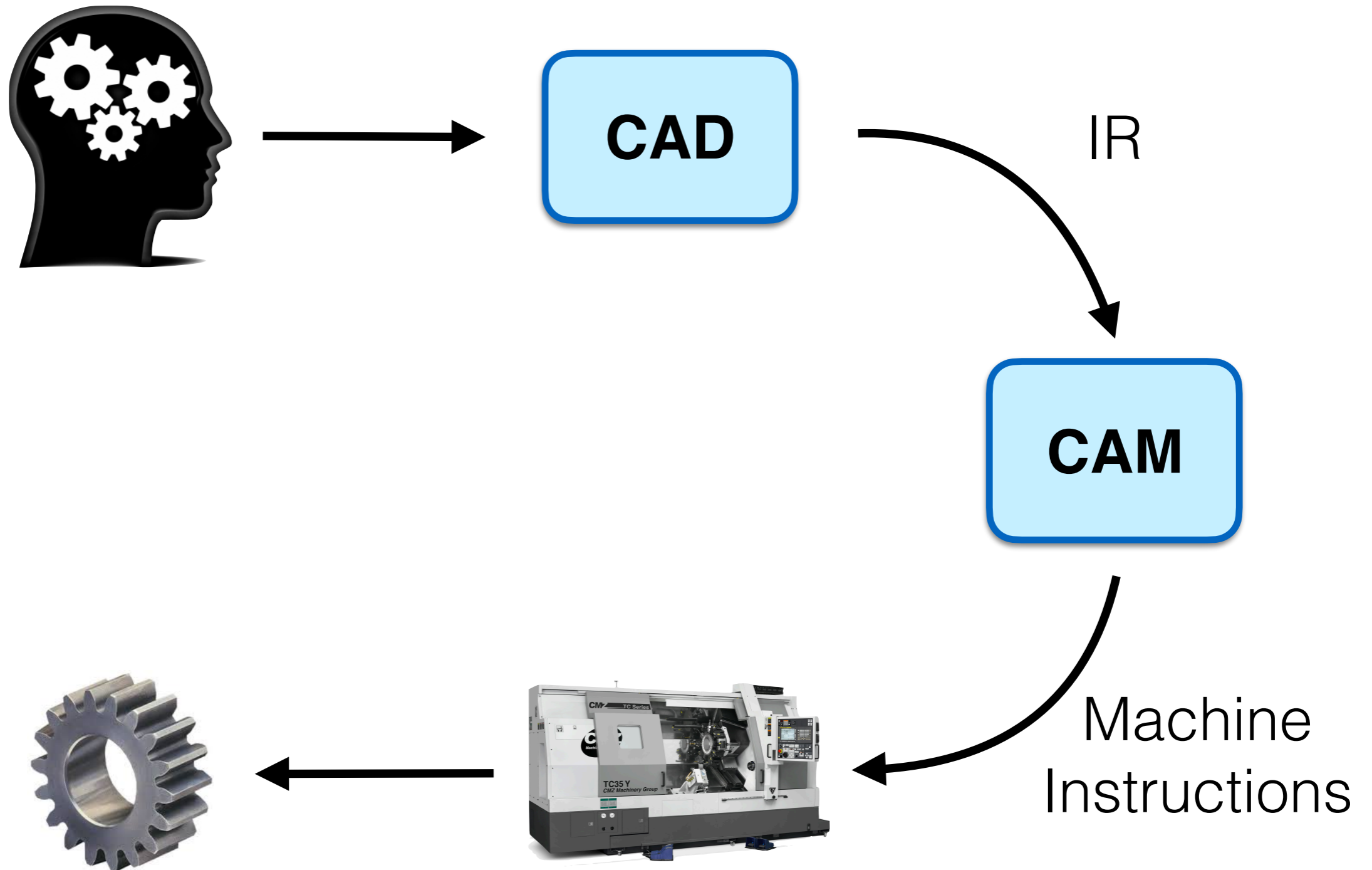
Computerized Manufacturing



Computerized Manufacturing



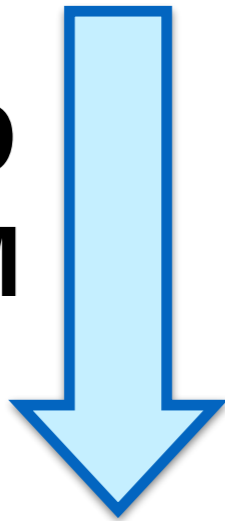
Computerized Manufacturing



CAD/CAM : Idea → Part



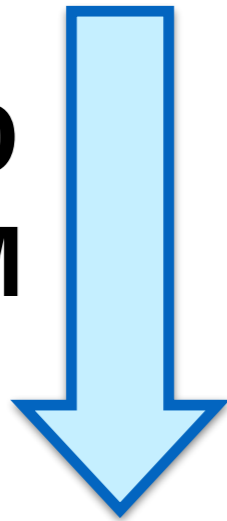
CAD
CAM



CAD/CAM : Idea \rightarrow Part



CAD
CAM



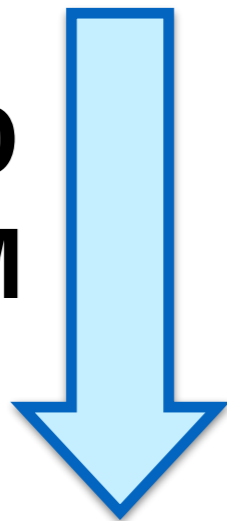
Where is the PL theory?

- semantics
- equivalence
- refinement
- approximation

CAD/CAM : Idea → Part



CAD
CAM

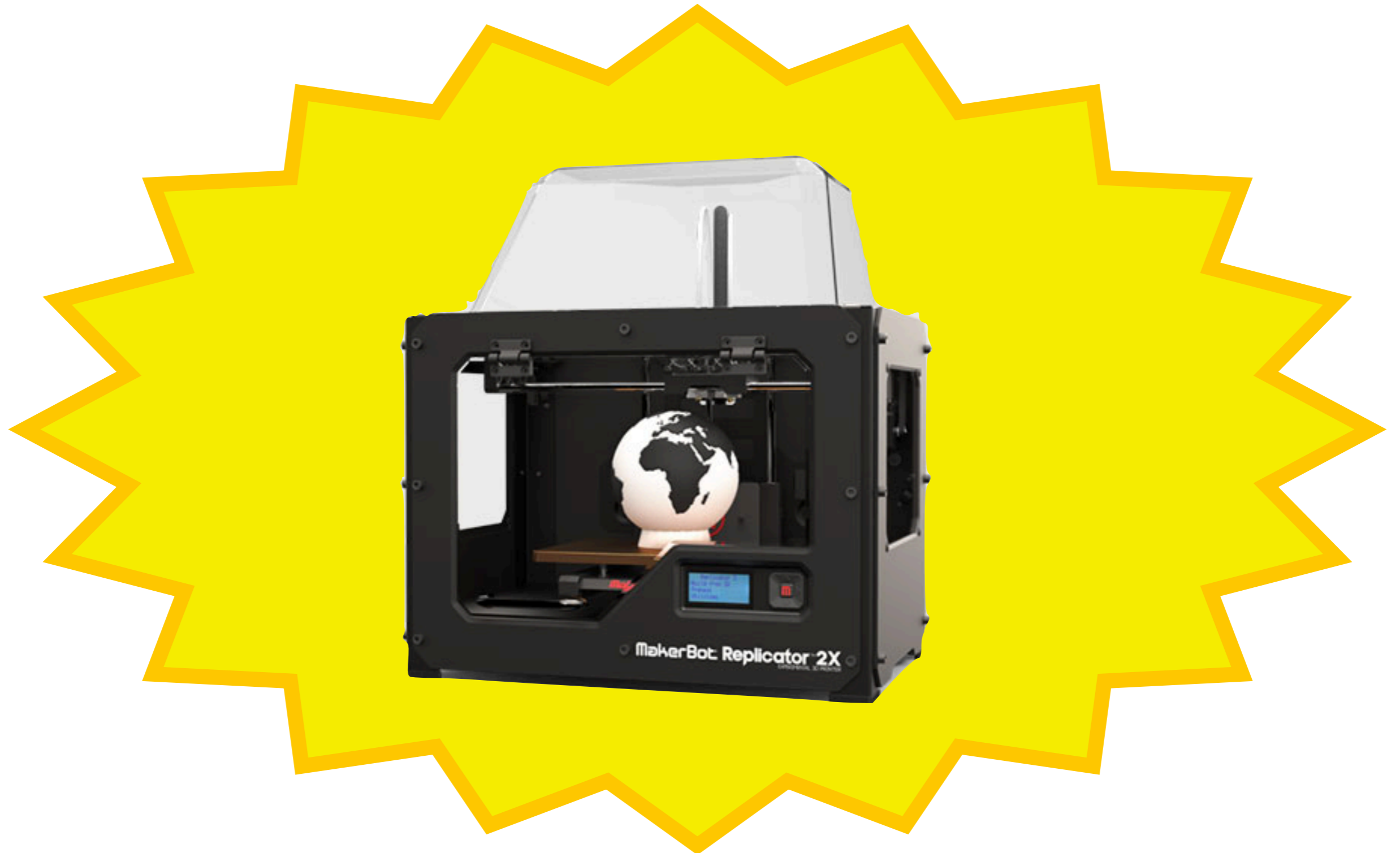


Where is the PL theory?

- semantics
- equivalence
- refinement
- approximation

Already worthy challenge,
but recently...

Democratized Manufacturing



3DP: PL Opportunity

3D Printing Background

Challenge: CAD Synthesis

Challenge: Slicing Framework



3D Printing Workflow



1. Design

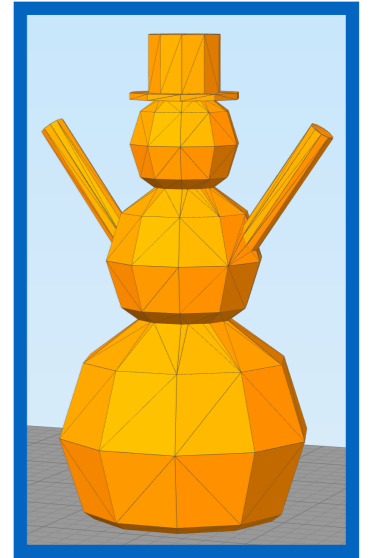


CAD

```
module snowman(scale, armAng) {  
  rs = [scale, scale / 1.6, scale / 2.3  
  chopBase(0.65 * rs[0]) {  
    sphere(r = rs[0]);  
    translate([0, 0, 0.85 * (rs[0] +  
    sphere(r = rs[1]);  
    translate([0, 0, 0.85 * (rs[1]  
    sphere(r = rs[2]);  
    translate([0, 0, 0.8 * rs  
    hat(scale);  
  scale, armAng);  
  for() arm(scale, armAng);  
}
```



STL



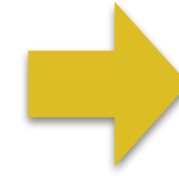


1. Design

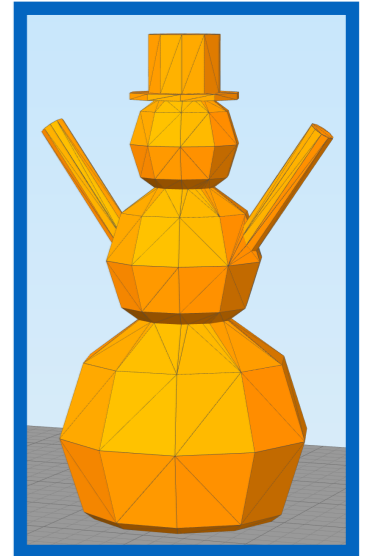


CAD

```
module snowman(scale, armAng) {
  rs = [scale, scale / 1.6, scale / 2.3
  chopBase(0.65 * rs[0]) {
    sphere(r = rs[0]);
    translate([0, 0, 0.85 * (rs[0] +
    sphere(r = rs[1]);
    translate([0, 0, 0.85 * (rs[1]
    sphere(r = rs[2]);
    translate([0, 0, 0.8 * rs
    hat(scale);
  }
  scale, armAng);
  for() arm(scale, armAng);
```



STL



2. Slice



```
G1 X97.097 Y100.000 F6000
G1 E0.0000 F2400
G92 E0
G1 X97.239 Y99.103 E0.0136 F412
G1 X97.651 Y98.294 E0.0272
G1 X98.294 Y97.651 E0.0408
G1 X99.103 Y97.239 E0.0544
G1 X100.000 Y97.097 E0.0680
G1 X100.897 Y97.239 E0.0816
G1 X101.706 Y97.651 E0.0952
G1 X102.349 Y98.294 E0.1088
G1 X102.761 Y99.103 E0.1223
G1 X102.903 Y100.000 E0.1359
G1 X102.761 Y100.897 E0.1495
G1 X102.349 Y101.706 E0.1631
```

G-code



1. Design

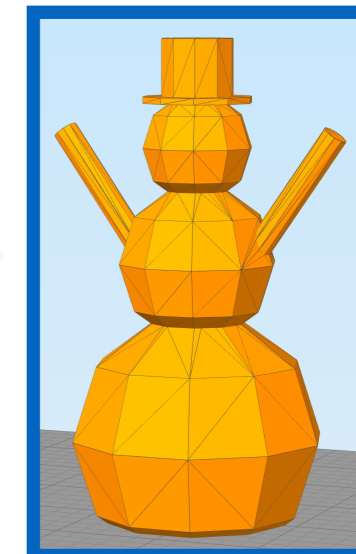


CAD

```
module snowman(scale, armAng) {  
  rs = [scale, scale / 1.6, scale / 2.3  
  chopBase(0.65 * rs[0]) {  
    sphere(r = rs[0]);  
    translate([0, 0, 0.85 * (rs[0] +  
    sphere(r = rs[1]);  
    translate([0, 0, 0.85 * (rs[1]  
    sphere(r = rs[2]);  
    translate([0, 0, 0.8 * rs  
    hat(scale);  
  scale, armAng);  
  arm() arm(scale, armAng);  
}
```



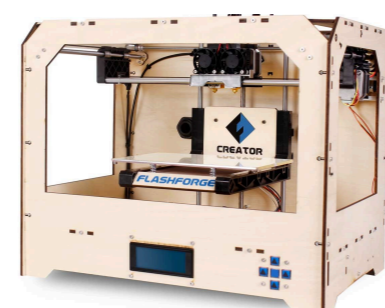
STL



2. Slice



3. Print



Marlin
SAILFISH

```
G1 X97.097 Y100.000 F6000  
G1 E0.0000 F2400  
G92 E0  
G1 X97.239 Y99.103 E0.0136 F412  
G1 X97.651 Y98.294 E0.0272  
G1 X98.294 Y97.651 E0.0408  
G1 X99.103 Y97.239 E0.0544  
G1 X100.000 Y97.097 E0.0680  
G1 X100.897 Y97.239 E0.0816  
G1 X101.706 Y97.651 E0.0952  
G1 X102.349 Y98.294 E0.1088  
G1 X102.761 Y99.103 E0.1223  
G1 X102.903 Y100.000 E0.1359  
G1 X102.761 Y100.897 E0.1495  
G1 X102.349 Y101.706 E0.1631
```

G-code



Part



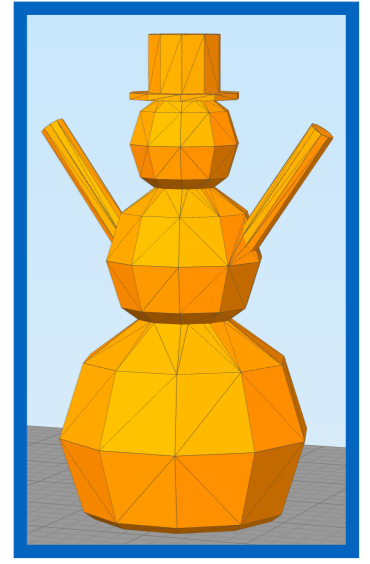
1. Design



CAD

```
module snowman(scale, armAng) {  
  rs = [scale, scale / 1.6, scale / 2.3  
  chopBase(0.65 * rs[0]) {  
    sphere(r = rs[0]);  
    translate([0, 0, 0.85 * (rs[0] +  
    sphere(r = rs[1]);  
    translate([0, 0, 0.85 * (rs[1]  
    sphere(r = rs[2]);  
    translate([0, 0, 0.8 * rs  
    hat(scale);  
  scale, armAng);  
  arm() arm(scale, armAng);  
}
```

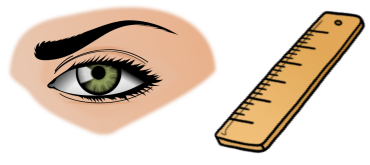
STL



2. Slice



4. OK?



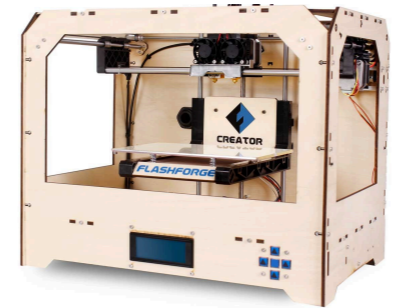
3. Print

```
G1 X97.097 Y100.000 F6000  
G1 E0.0000 F2400  
G92 E0  
G1 X97.239 Y99.103 E0.0136 F412  
G1 X97.651 Y98.294 E0.0272  
G1 X98.294 Y97.651 E0.0408  
G1 X99.103 Y97.239 E0.0544  
G1 X100.000 Y97.097 E0.0680  
G1 X100.897 Y97.239 E0.0816  
G1 X101.706 Y97.651 E0.0952  
G1 X102.349 Y98.294 E0.1088  
G1 X102.761 Y99.103 E0.1223  
G1 X102.903 Y100.000 E0.1359  
G1 X102.761 Y100.897 E0.1495  
G1 X102.349 Y101.706 E0.1631
```

G-code



Part



Marlin
SAILFISH



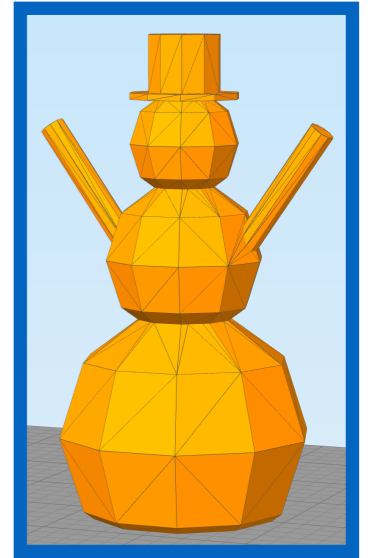
1. Design



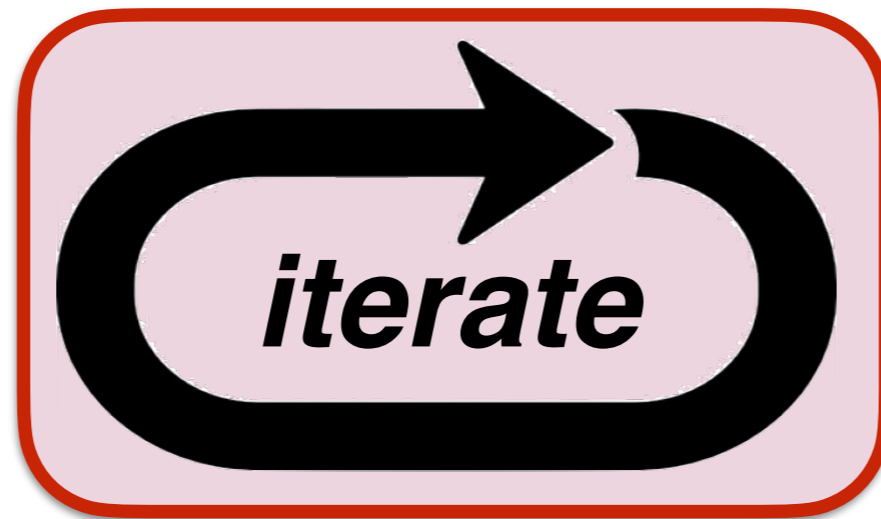
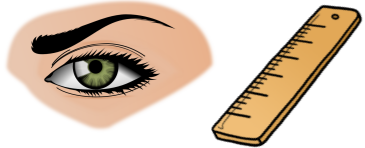
CAD

```
module snowman(scale, armAng) {
  rs = [scale, scale / 1.6, scale / 2.3
  chopBase(0.65 * rs[0]) {
    sphere(r = rs[0]);
    translate([0, 0, 0.85 * (rs[0] +
    sphere(r = rs[1]);
    translate([0, 0, 0.85 * (rs[1]
    sphere(r = rs[2]);
    translate([0, 0, 0.8 * rs
    hat(scale);
  scale, armAng);
  for() arm(scale, armAng);
```

STL



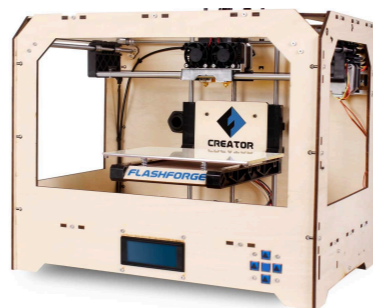
4. OK?



2. Slice



3. Print



SAILFISH

```
G1 X97.097 Y100.000 F6000
G1 E0.0000 F2400
G92 E0
G1 X97.239 Y99.103 E0.0136 F412
G1 X97.651 Y98.294 E0.0272
G1 X98.294 Y97.651 E0.0408
G1 X99.103 Y97.239 E0.0544
G1 X100.000 Y97.097 E0.0680
G1 X100.897 Y97.239 E0.0816
G1 X101.706 Y97.651 E0.0952
G1 X102.349 Y98.294 E0.1088
G1 X102.761 Y99.103 E0.1223
G1 X102.903 Y100.000 E0.1359
G1 X102.761 Y100.897 E0.1495
G1 X102.349 Y101.706 E0.1631
```

G-code



Part

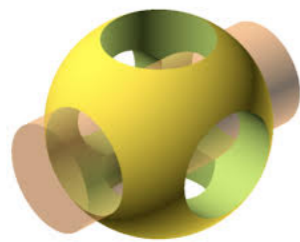
3DP: PL Opportunity

3D Printing Background

Challenge: CAD Synthesis

Challenge: Slicing Framework

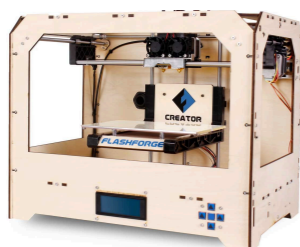
Challenge: CAD Synthesis



: CAD → STL



: STL → G-code

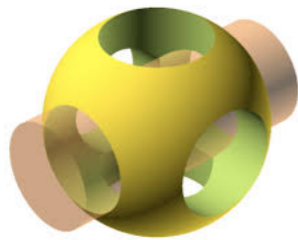


: G-code → Part

Challenge: CAD Synthesis



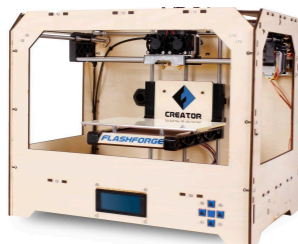
: Idea → CAD



: CAD → STL



: STL → G-code



: G-code → Part

Today: Crowdsource Designs



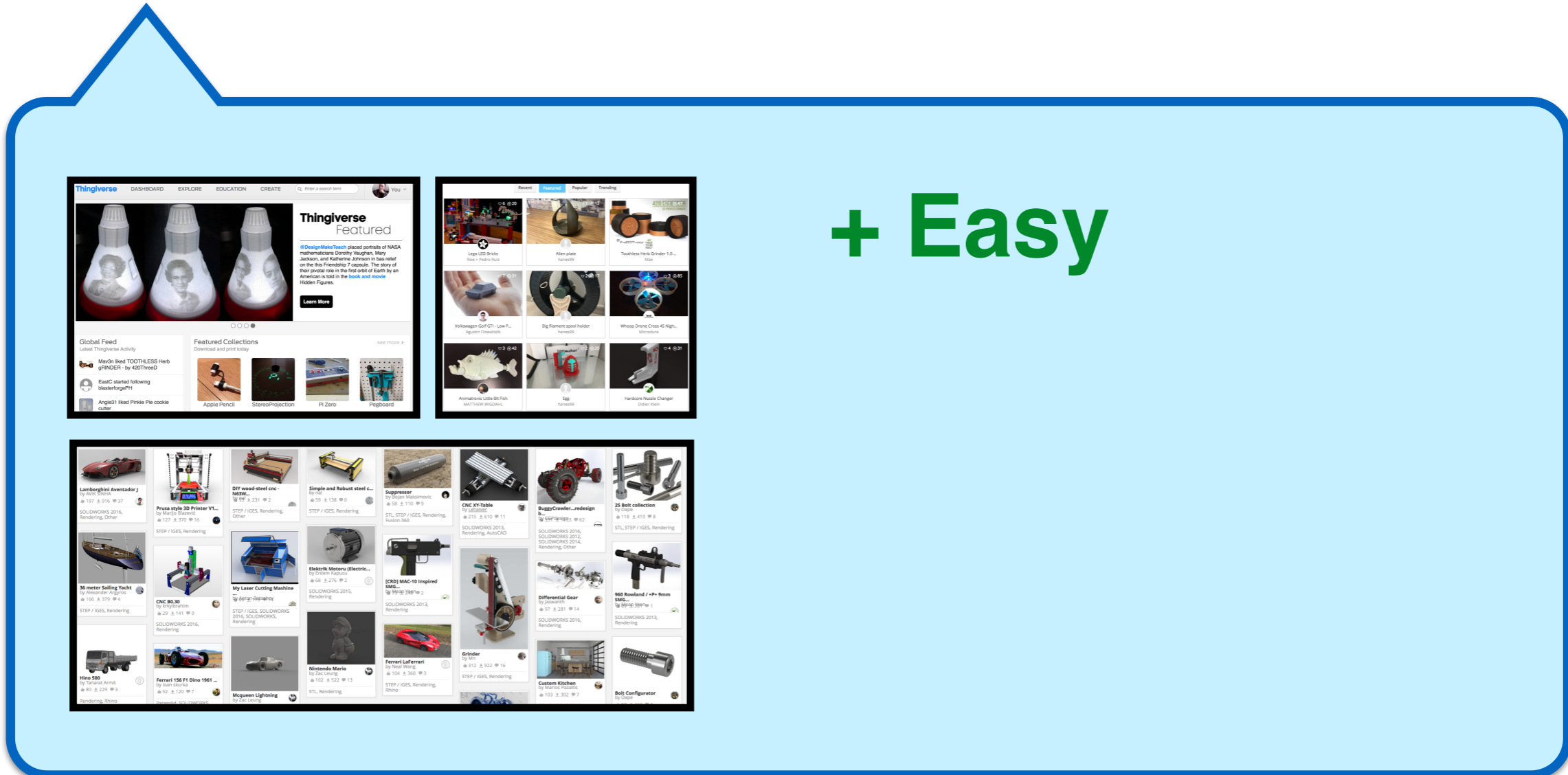
: Internet → Idea → STL



Today: Crowdsourced Designs



: Internet → Idea → STL

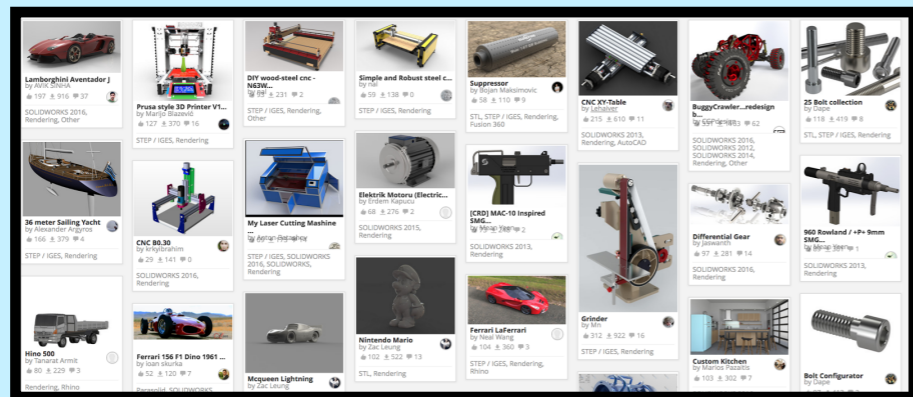
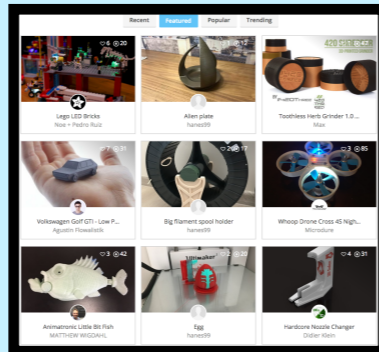
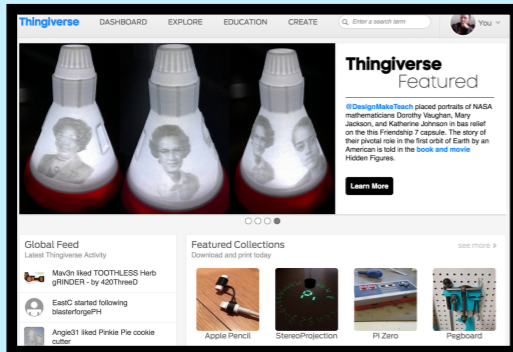


+ Easy

Today: Crowdsourced Designs



: Internet → Idea → **option** STL



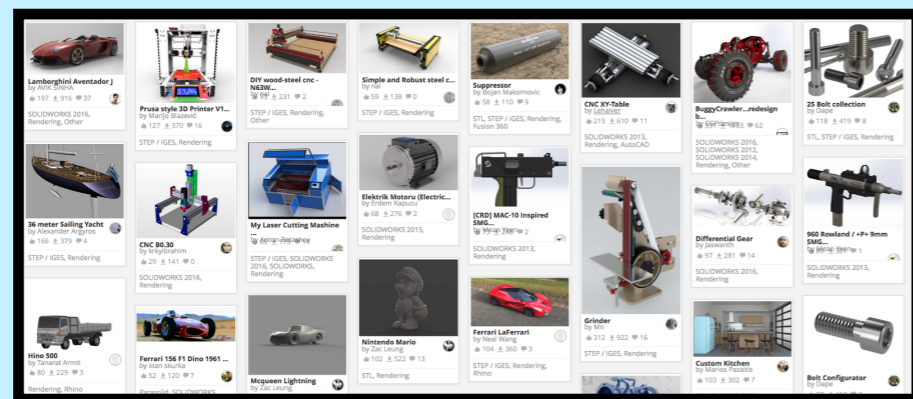
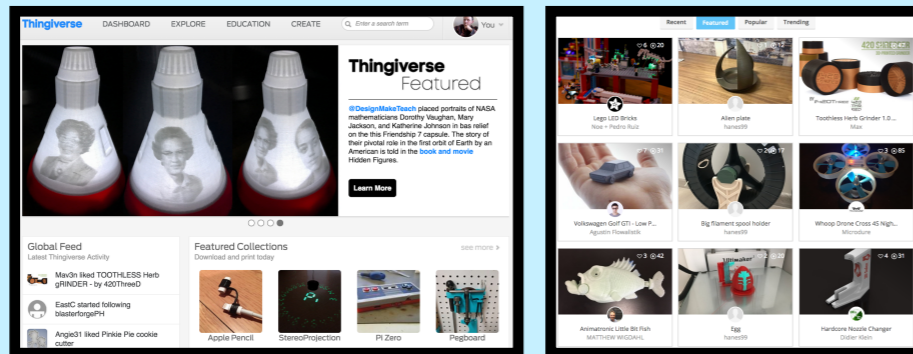
+ Easy

- Incomplete

Today: Crowdsourced Designs



: Internet → Idea → **option** STL



+ Easy

- Incomplete

- Hard to modify

Today: Crowdsource Designs

Thingiverse

: Internet → Idea → **option** STL

YM **GRABCAD**

Goal

For idea **i**, even when:

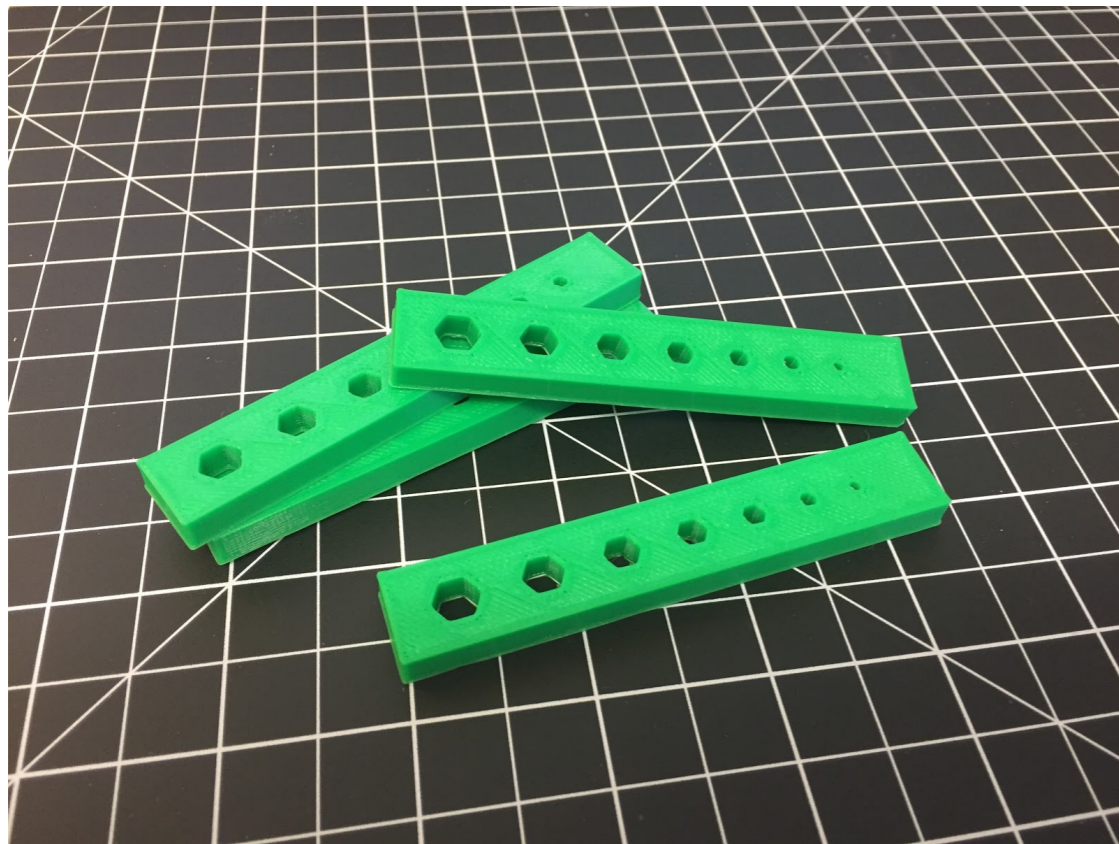
Thingiverse (☁, **i**) = **None**

there often exists similar **i'** such that:

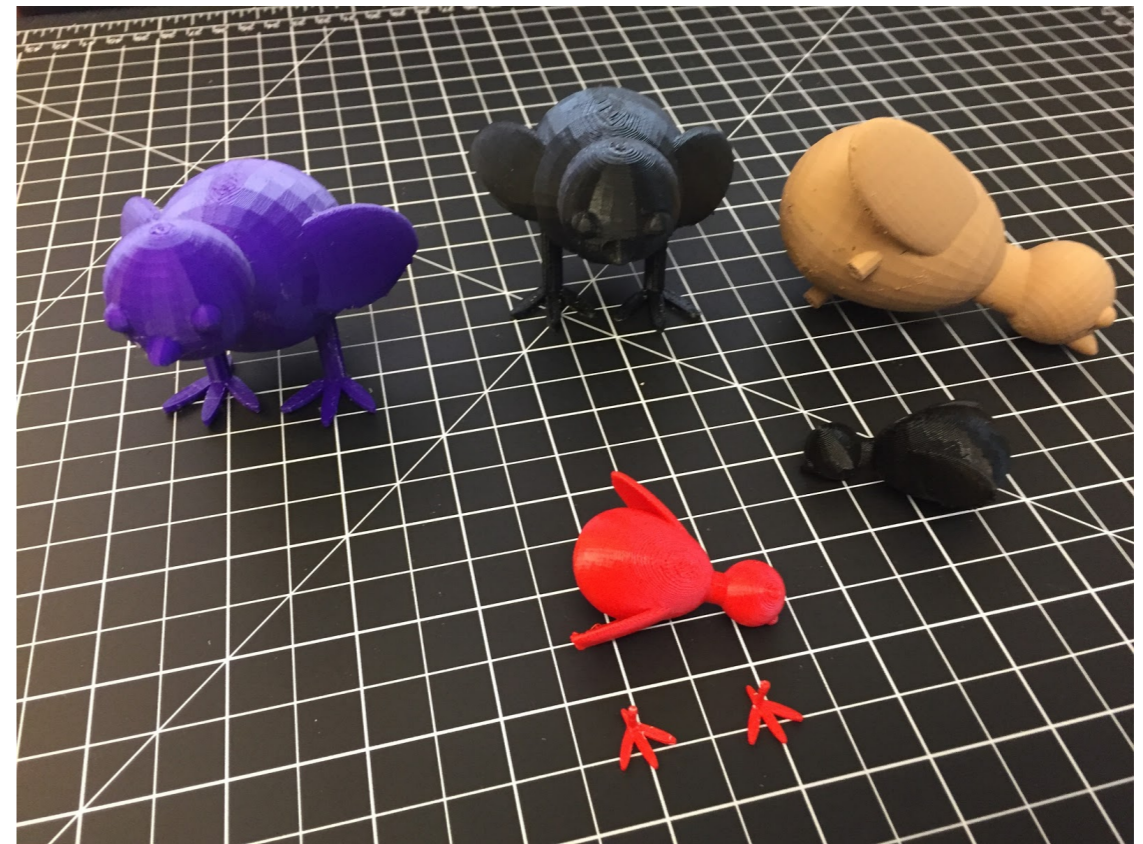
Thingiverse (☁, **i'**) = **Some s**

So: adapt “almost” design **s** to a design for **i**!

Example “Almost” Designs

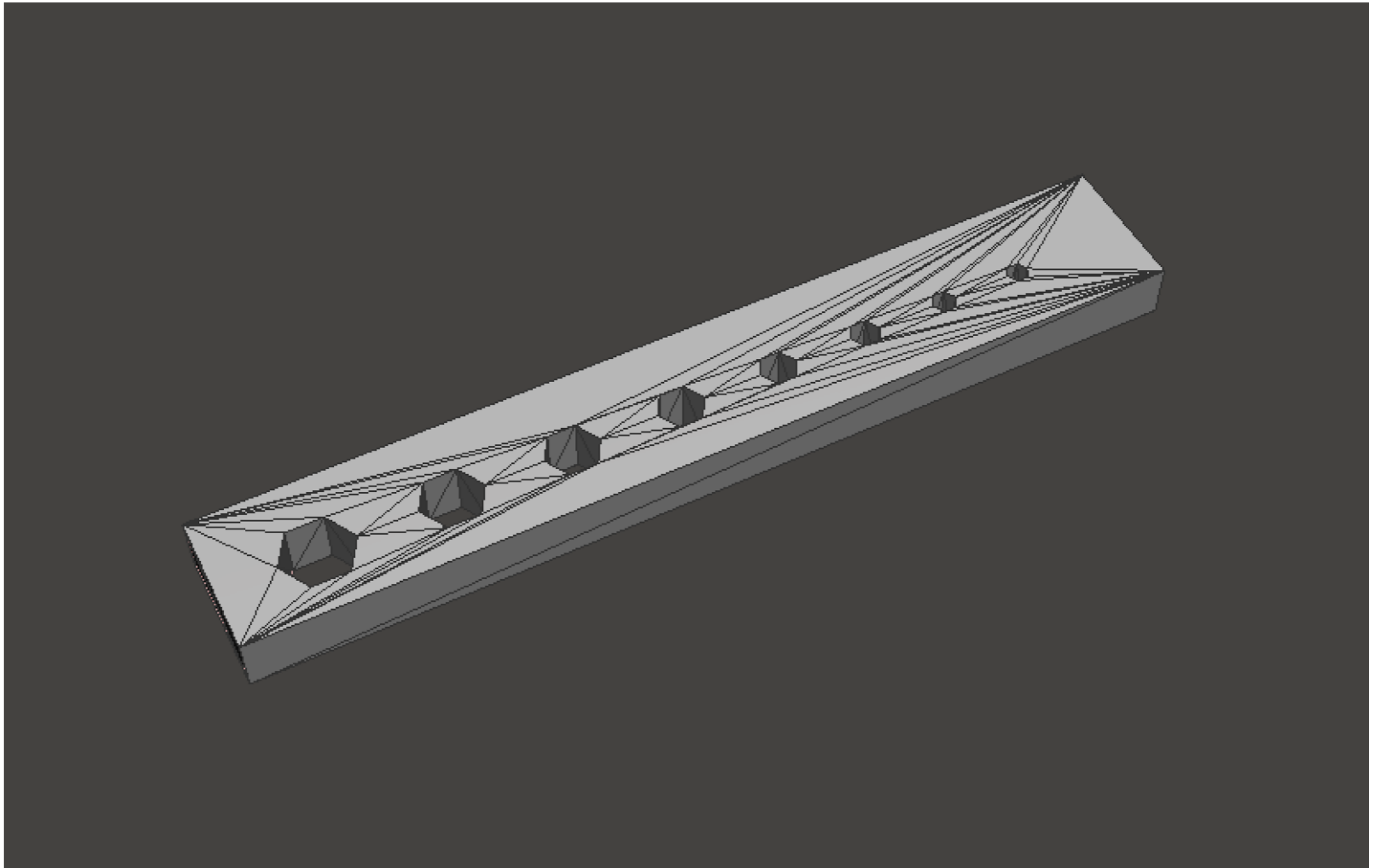


Rotated Hex Hole

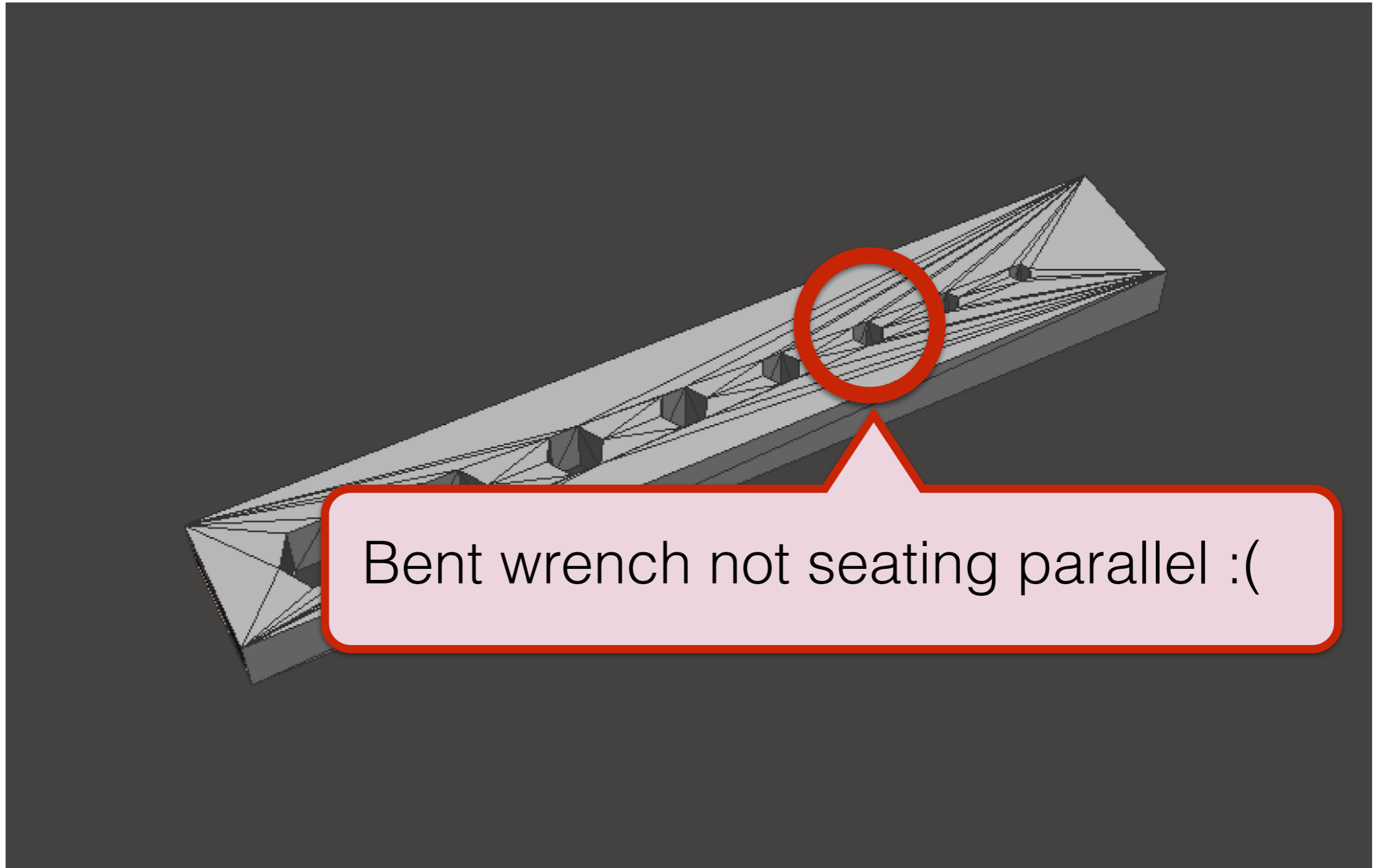


Broken Chicken Legs

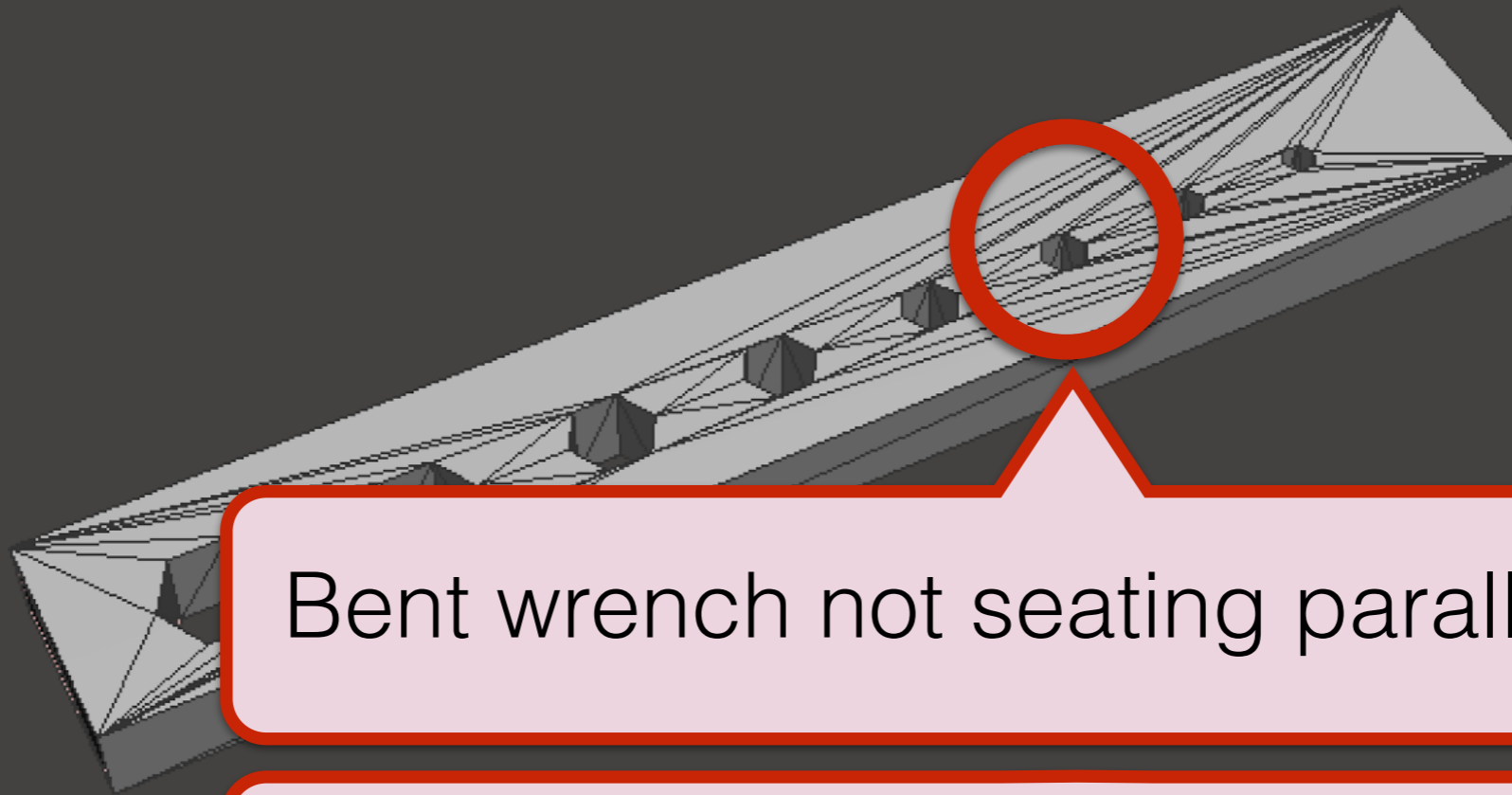
Inferring CAD to fix hex holder



Inferring CAD to fix hex holder



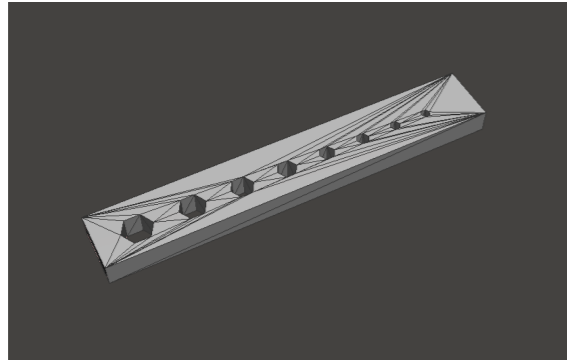
Inferring CAD to fix hex holder



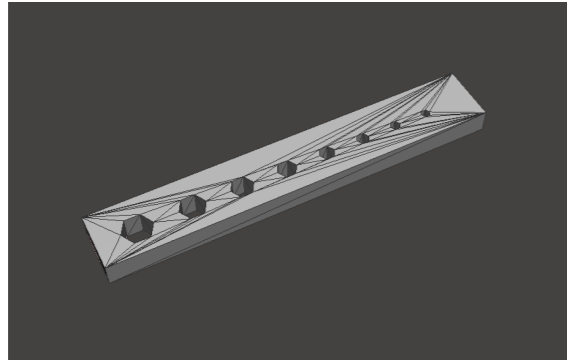
Bent wrench not seating parallel :(

Simple mesh editing broke model.

Inferring CAD to fix hex holder



Inferring CAD to fix hex holder

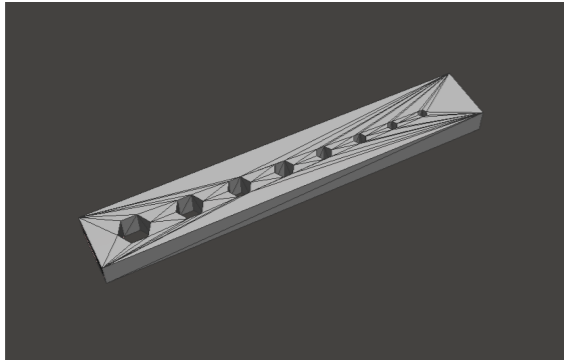


Infer
→
(manual)

```
difference() {  
  cube([w, d, h]);  
  for(i = [0 : len(holes) - 1])  
    translate([offset(i), d/2, -1])  
    hex_hole(holes[i]);  
}
```



Inferring CAD to fix hex holder



Infer
→
(manual)

```
difference() {  
  cube([w, d, h]);  
  for(i = [0 : len(holes) - 1])  
    translate([offset(i), d/2, -1])  
    hex_hole(holes[i]);
```

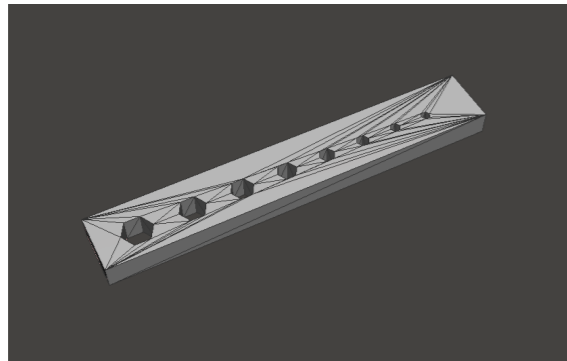


Tweak ↓ (small)

```
difference() {  
  cube([w, d, h]);  
  for(i = [0 : len(holes) - 1])  
    translate([offset(i), d/2, -1])  
    if(i == 5)  
      rotate([0, 0, 35])  
      hex_hole(holes[i]);  
    hex_hole(holes[i]);
```



Inferring CAD to fix hex holder



Infer
→
(manual)

```
difference() {  
  cube([w, d, h]);  
  for(i = [0 : len(holes) - 1])  
    translate([offset(i), d/2, -1])  
    hex_hole(holes[i]);  
}
```

Tweak ↓ (small)

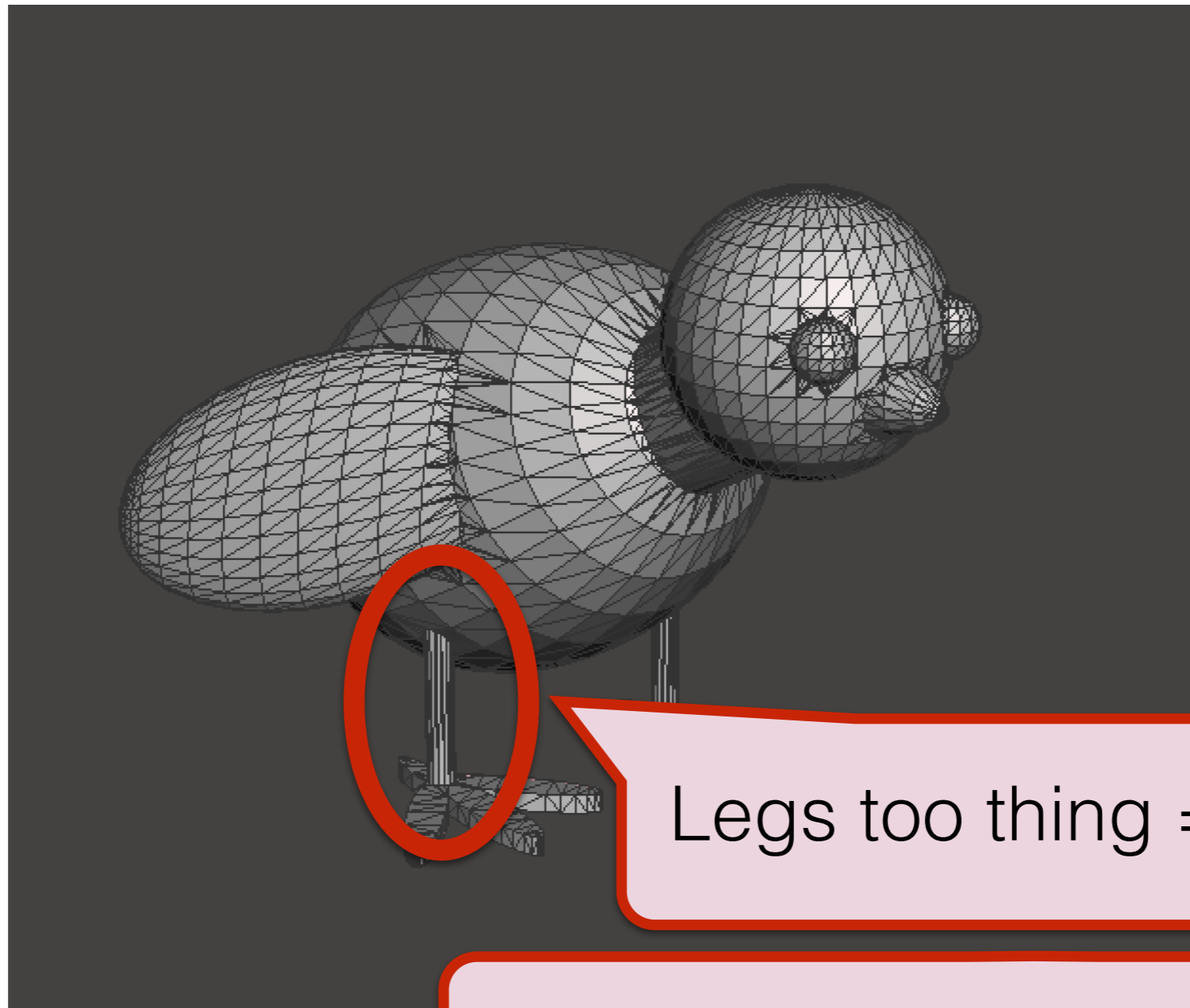


(success)

←
Print

```
difference() {  
  cube([w, d, h]);  
  for(i = [0 : len(holes) - 1])  
    translate([offset(i), d/2, -1])  
    if(i == 5)  
      rotate([0, 0, 35])  
      hex_hole(holes[i]);  
    hex_hole(holes[i]);  
}
```

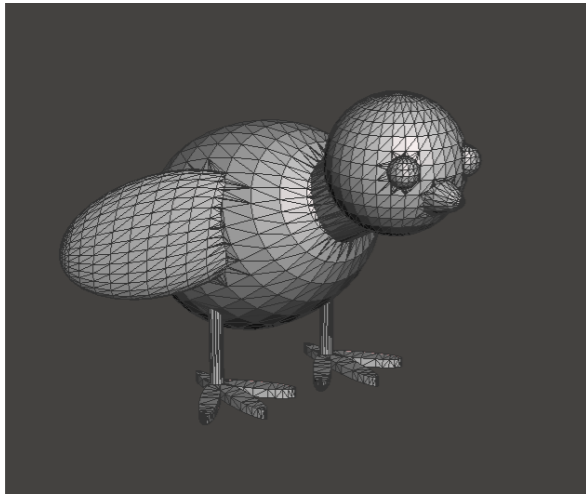
Inferring CAD to fix chicken



Legs too thin => broke!

Expanding leg in STL tedious.

Inferring CAD to fix chicken



Infer
→
(manual)

```
...  
cylinder(h = 30, r = 2);  
cylinder(h = 30, r = 2);  
...
```

Tweak ↓ (small)



Print
←

```
...  
cylinder(h = 30, r = 4);  
cylinder(h = 30, r = 4);  
...
```

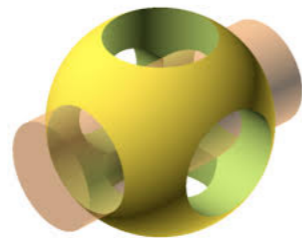
(success)

Challenge: CAD Synthesis

decompiler



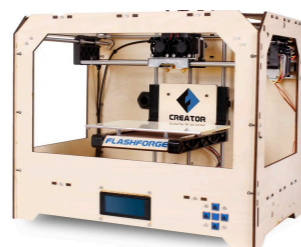
: Internet → Idea → CAD



: CAD → STL



: STL → G-code



: G-code → Part

3DP: PL Opportunity

3D Printing Background

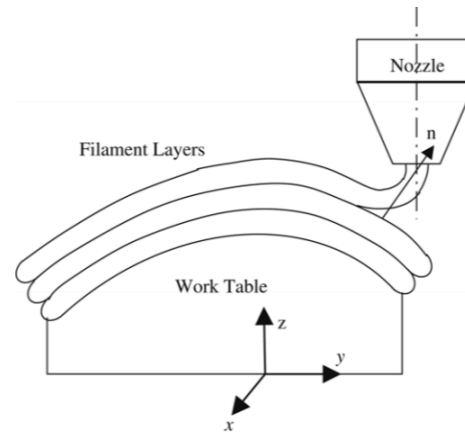
Challenge: CAD Synthesis

Challenge: Slicing Framework

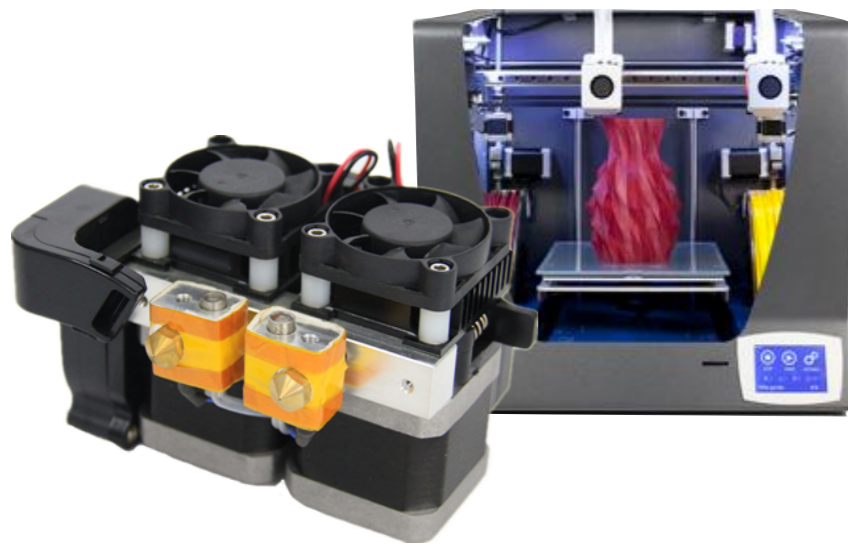
Exploring Slicing Strategies



Partitioning [Chopper 12]



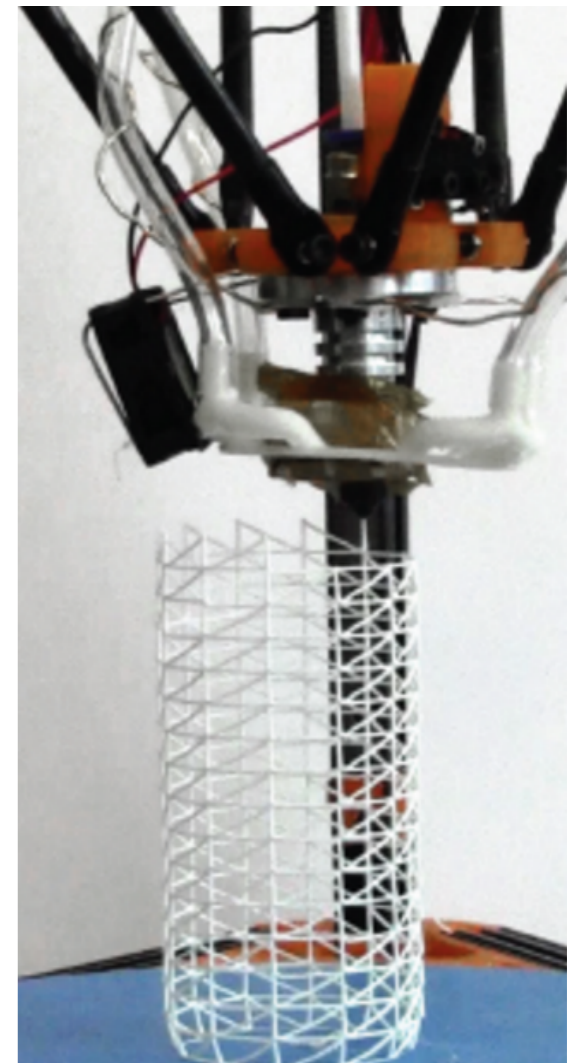
Curved Layer FDM [CAD 08]



Parallelization



Multi-material [OpenFab 13]



Approx [Wireprint 14]

3DP Slicing Framework

Today: roll your own framework

Goal: LLVM / CIL for 3D Printing

Should enable exploring many new strategies:

- error compensation
- G-code synthesis with Z3
- parallelizing peepholes
- cross-part constraint
- ...

3DP: PL Opportunity

Solid foundation:

- compiler theory
- fast solvers
- diverse synthesis
- num. methods

Goals:

- fab theory
- efficiency
- self-stabilize
- tools

Compilers generate
our environment.

Compilers generate
our environment.

PL folk can develop the
tools to make it better.

Thank You!

Compilers generate
our environment.

PL folk can develop the
tools to make it better.